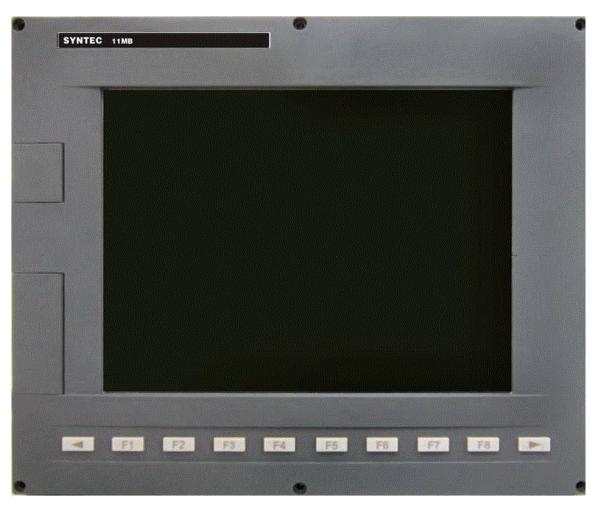


11B SERIES



Date: 2014/06/19





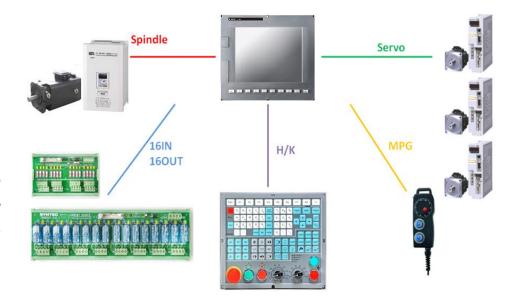
11B Controller Description

The Syntec 11B Series controllers incorporate embedded system architectures with 10.4-inch LCD displays. They include integrated servo axes, spindle axes, MPG (manual pulse generator) axes, as well as USB ports on the front panel. This series provides low prices, high stability, easy operation, and high reliability.

- The lathe and miller come standard with 8 sets of axial directions
- 2 spindle DA (+/-10V) sets
- 1 set of dedicated MPG (manual pulse generator) axes, including 7 IN points
- Comes standard with 64I/64O, expandable to 128I/128O
- Dedicated RS-485 communications port
- Dedicated port on the operation panel for matrix scanning

- 1 USB port on the front panel
- Adapter (100~240V AC 50/60Hz) included
- Operating environment temperature: 55°C

The 11B Architecture





Product Features

Complete System Functionality

The system provides complete lathing and milling functionalities, a simple windows-based operating interface that is easy to learn to use, and precise synchronous movement interpolation, allowing users to easily produce

perfected work pieces.





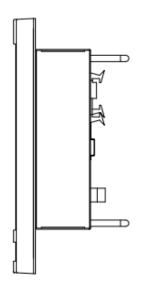
Advanced Transmission Mechanism

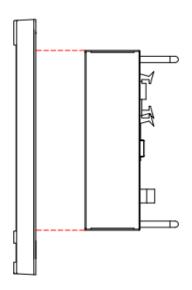
In addition to the traditional RS-485 interface, the system also has an advanced 10/100 MHz Ethernet port as well as hot-swappable USB ports, which boost software transmission speeds as well as enhance convenience and stability.



Easily Maintainable System Architecture

This next-generation controller is built using high-density integration technologies and incorporates an extremely well-thought-out design. Its compact and modular design allows on-site personnel to easily perform maintenance with just a single screwdriver.









User-Friendly Operation Interface

□Simulation

- -Syntax check
- -3D simulation and step simulation
- -Magnify at any ratio
- -Integrated environment that can also check trajectory coordinates and program contents



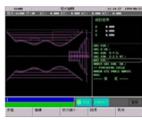
☐Graphical Dialogue

- -X/Y axis single/dual-direction surface milling cycles
- -Track-type/square-type/round-type trench processing cycles
- -Round-hole/angled-line hole/curved-hole checkerboard hole drilling cycles



■Multi-pocketed Complex Cutting cycle

- -The user only needs to enter the external appearance of the work piece, and the CNC will automatically figure out the cutting path and cycle
- -Can be used with A, R, and C
- -Can perform multi-pocketed processing with one run of the program $\,$



□Processing execution

- -Integrated operation environment
- -Processing parameter configuration
- -Program coordinate and cutting tool configurations are made on the same page



☐ Hand Wheel Processing Simulation

The MPG can be used to control software processing speeds

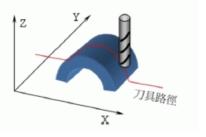
Rotate the MPG forwards/backward to move the cutting tool

forwards/backwards along its path

Turn the MPG to fast and the cutting tool will move faster along its path

Turn the MPG to slow and the cutting tool will move slower along its path

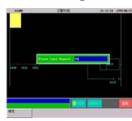
Turn the MPG to stop and the machine will stop



Thoughtful Diagnostic and Development Tools

☐On line ladder

- -I, O, C, S inspection page
- -Real-time Ladder display
- -Search for components
- -The PLC can issue alert messages in Chinese and English



□Parameter Settings

- -Parameter group configuration
- -Comprehensive descriptions of the meaning of parameters
- -Password protection
- -Supports user-defined parameters



□Alert records

- -Records 200 alert messages in the alert history, with dates, hours, minutes, seconds, and alert content
- -Capable of further displaying reason for malfunction and methods used for troubleshooting



□Production Records

- -Provides complete records for 100 completed processing programs, including the program name, start time, total processing time, as well as number of work pieces
- -Monitors the production rate of programs in execution





Complete Software Application Support

□MACRO Support

- -Windows based Macro development environment
- -Can communicate with the PLC via register bits
- -Completely compatible with CNC operating environments



- -Open and store files
- -Step simulation and three-view diagram simulation
- -System parameter and variable configuration

Macro Syntax

Logic Computation Command

- ◆ AND, OR, XOR,...
- ♦ +, -, ×, 1, . . .
- ♦ <.=.>....

Digit Function Command

- ..., MAT, 200, MI2◆
- ◆ ASIN, ACOS, ATAN,...
- ◆ SQRT,...
- ◆ MAX,MIN

Structural Flow Control Command

- ◆ GOTO
- ◆ IF < > THEN END IF
- ♦ WHILE < > DO END_WHILE

□Ladder Support

- -Windows based PLC software development
- -Online Ladder display, making troubleshooting easier
- -PLC executes servo movement commands

SALE STATE BALL STATE (SALE) SALE (SALE) S

-Editing Function Table

- Open file, save file
- Add Ladder footnote (Chinese and English)
- Cut, copy, paste
- Search,...
- Syntax check

Ladder Syntax

- Contact point: normally open, normally closed
- Coil: normally open, normally closed, positive edge, negative edge, always return
- **♦** Arithmetic commands:
- **♦** Timer, counter
- Data movement: MOV
- **♦** Cutting tool commands: ROT
- ♦ Software control commands: JMP, JSR
- **♦** Call subroutine
- Directly execute PLC shaft movement command
- Specify PLC shaft for executing movement program instruction

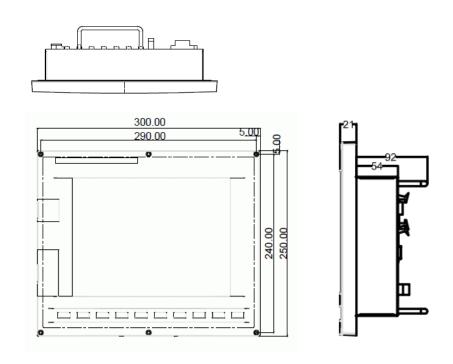
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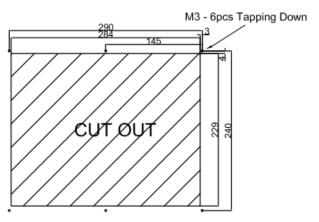


■ External Appearance of the Product (11B-SEP-DG)



■ Structural Dimensions (11B-SEP-DG)







Connector Interface Definitions

Please mind the voltage values as well as positive and negative polarities

RIO Connector Definitions

RIO	PIN	SIGNAL	PIN	SIGNAL
	1	RIO_1_Tx+	6	RIO_2_Tx+
(60)	2	RIO_1_Tx-	7	RIO_2_Tx-
0 0	3	RIO_1_Rx+	8	RIO_2_Rx+
(; ;	4	RIO_1_Rx-	9	RIO_2_Rx-
	5	NC₽		

HK Connector Definitions

НК	PIN	SIGNAL	PIN	SIGNAL
	26	100 0	25	XDI55
	24	XDI54	23	XDI53
26 25	22	XDI52	21	XDI51
	20	XDI50	19	XDI49
	18	XDI48	17	5V
	16	GND	15	XDO62
	14	XDO61	13	XDO60
	12	XDO59	11	XDO58
	10	XDO57	09	XD056
	08	XDO55	07	XDO57
2 1	06	XDO53	05	XDO52
	04	XDO51	03	XDO50
	02	XDO49	01	XDO48

SPINDLE Connector Definitions

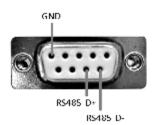
SPINDLE	PIN	SIGNAL
1 4	1	DA-
	2	DA-
	3	DA+
	4	DA+

● P1~P8 Connector Definitions

	P1~P8↔	PIN	SIGNAL	PIN	SIGNAL	PIN	SIGNAL
	0	1	A+	6	Z+	11	CW+
1	(B 10 0	2	A-	7	ALM+(+24V)	12	CW-
1	000	3	B+	8	ALM-(GND)	13	CCW+
1	no i	4	B-	9	SERVO-ON	14	CCW-
	0	5	Z+	10	SERVO-CLR	15	OUT_COM

RS485 Connector Definitions

RS485₽	PIN	SIGNAL	PIN	SIGNAL
	1	. 200 -	6	TXD485-
(29)	2		7	TXD485+
0000	3		8	NC
99	4		9	5V
	5	GND		



Wiring-Side RS485 Front Schematic Diagram

MPG Connector Definitions

MPG	PIN	SIGNAL	PIN	SIGNAL	PIN	SIGNAL
0	1	MPG_A+	6		11	XDI 60
(B 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	2	MPG_A-	7	XDI56₽	12	XDI 61
000	3	MPG_B+	8	XDI 574 ³	13	XDI 62
no o	4	MPG_B-	9	XDI 584 ³	14	GND
0	5		10	XDI 59₽	15	+5V



■ 11B Series Product Specifications

O Standard

Not supported

 \triangle Optional

Product Specifications					
Model	11TB	11MB			
Control command format	Generic				
Largest main system axis group		2			
Largest PLC axis group number		1			
Standard control axis number	8	6			
Maximum control axis number (optional)	8	6			
Maximum spindle number	6	4			
Maximum synchronous control axis number (single axis group)		4			
Smallest unit of control - mm	0.0001				
Maximum number of work piece coordinate sets	100				
Maximum number of tool compensation sets	aximum number of tool compensation sets 96				
Number of pre-read single-sections	1000				
Single-section processing time – number of single sections / seconds	500	1000			
Hardware Specifications					
I/O (standard)	64	/64			
I/O (optional)	/O (optional) 128/128				
DA	2				
Display 10.4					
RJ-45		1			
VGA output	-	_			

PS/2	-	_
RS232/RS422/RS485	- /-	- /1
CF card	-	_
USB	-	L
Compensation		
Model	11TB	11MB
Backlash compensation	()
Pitch error compensation	()
Angle compensation	()
Temperature-rise compensation	()
Two-dimensional compensation	()
Operation		
MPG simulation	()
Program idle	0	
Selective stop	0	
Single-section execution	()
Virtual MPG	()
Pause point activation	()
Break point activation	()
External offset settings	()
MPG offset function	_	0
Program Input		
Selective jump	()
B-stop / end of program	()
Interrupt-type MACRO (M96/M97)	()
M198 subroutine call	()
G code expansion)





High-Speed, High-Precision				
Model	11TB	11MB		
Constant Jerk control	0			
Cross-section S-curve acceleration and deceleration	0			
Automatic corner deceleration	()		
Circular radius speed limit	()		
Multiple sets of high-speed high-precision parameters	_	0		
Fast user parameters	_	0		
SPA function	_	0		
Virtual circular radius function	_	0		
High-speed high-precision control mode I (G05.1Q1)	_	0		
High-speed high-precision control mode II (G05P10000)	_	Δ		
NURBS interpolation	_	Δ		
Tool and Blade Management				
Automatic blade calibration	0			
Tool and blade usage life management	()		
Supportive Functions				
Mechanical lock (R-bit)	()		
Software cycle limit	()		
Spindle rotation speed detection	()		
Axial coupling function	()		
Dynamic axial coupling function	0			
Feedback coupling function O				
Fast tapping retraction	0			
Virtual axis function	Virtual axis function O			
Axis swapping function	()		
Serial machine swapping function	-	_		

Fast controller-based spindle positioning (C61)	0
Frond and back Dipole architecture	0
Data backup and restoration (MB)	0
Boot screen customization	0
Favorites	0
Project protection function	0
Access privilege management	0
RemoteAP monitoring	0
Programming	
Background editing	0
Editing protection	0
Data Transfer Function	
NETWORK/FTP	0/0
DNC(Network)	0
DNC(USB)	0
Information Display	
Craphical cimulation	
Graphical simulation	0
Optical scale missing pulse self-diagnostics	0
·	-
Optical scale missing pulse self-diagnostics	-
Optical scale missing pulse self-diagnostics Five-Axis Function	-
Optical scale missing pulse self-diagnostics Five-Axis Function Five-axis blade tip control (RTCP)	-
Optical scale missing pulse self-diagnostics Five-Axis Function Five-axis blade tip control (RTCP) Characteristic coordinate system (tilted-surface)	-
Project protection function Access privilege management RemoteAP monitoring Programming Background editing	0 0 0



■ G Code Commands

Model	11TB
Elliptical cutting (clockwise) (G02.1)	0
Parabolic cutting (clockwise) (G02.2)	0
Cylindrical interpolation (G07.1)	0
Activate polar coordinate interpolation (G12.1)	0
External radius / internal radius lathing and cutting cycle (G20)	0
Threaded lathing and cutting cycle (G21)	0
Threaded lathing and cutting mid-phase blade entry cycle (G21.2)	0
Edge and surface lathing and cutting cycle (G24)	0
Jumping function (G31)	0
Thread cutting (G33)	0
Variable-pitch thread cutting (G34)	0
Blade tip control (G43.4)	1
Polygonal cutting (G51.2)	0
Blade calibration for tilted surface processing (G53.1)	ı
Operating coordinate system	0
Mirroring function (lathe) (G68)	0
Tilted surface processing (G68.2)	1
Duplex cutting cycles (G72~G78)	0
Fixed drilling cycles (G80,G83~G89)	0
Default absolute zero coordinated system (G92.1)	0
Inversed time feed (G93)	0
Equal surface cutting speeds (G96)	0
Spindle synchronization function (G114.1)	0
Spindle bearing function (G114.3)	0

Model	11MB
High-speed high-precision mode (G05)	0
Path smoothing mode (G05.1)	0
NURBS curve interpolation (G06.2)	0
Thread cutting (G33)	0
Automatic blade measurement command (G37)	0
Blade offset (G45~G48)	0
Tilted surface processing (G68.2)	0
High-speed pecking-type drilling cycle (G73)	0
Left-handed tapping cycle (G74)	0
Fine boring cycle (G76)	0
Drilling cycle (G81)	0
Suspended hole-bottom drilling cycle (G82)	0
Pecking-type drilling cycle (G83)	0
Tapping cycle (G84)	0
Drilling cycle (G85)	0
High-speed drilling cycle (G86)	0
Backside fine boring cycle (G87)	0
Semi-automatic fine boring cycle (G88)	0
Suspended hole-bottom boring cycle (G89)	0



■ 11B Series Operating Environment

Model	11B
Operating environment	-10 ~ 55°C
Storage environment	-40 ~ 70°C
Cooling method	Natural cooling
Safety certification	CE
Operating voltage	100V~240V, 60Hz
Power consumption	Approximately 5W